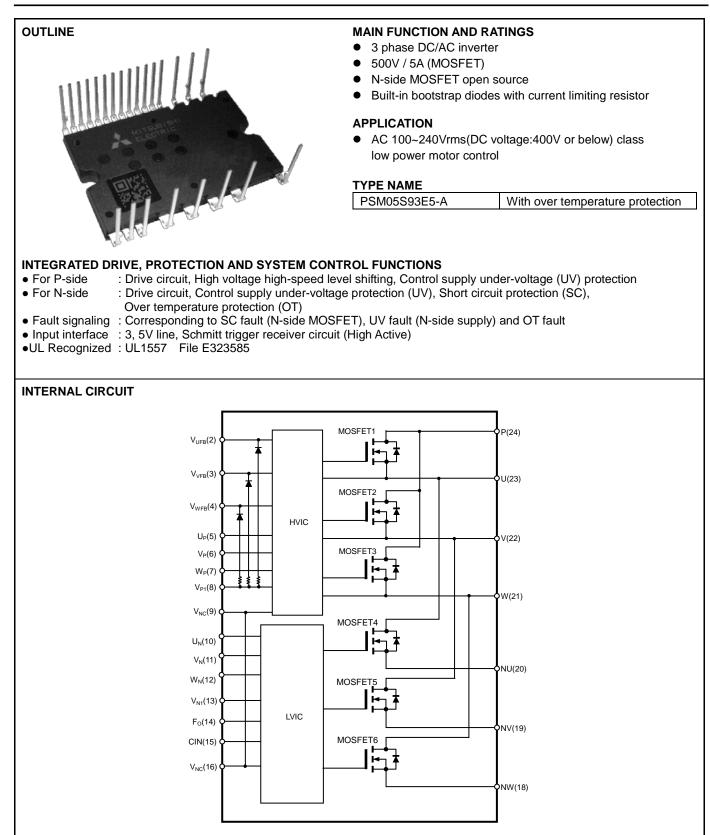


INSULATED TYPE



### **MAXIMUM RATINGS** ( $T_{ch} = 25^{\circ}C$ , unless otherwise noted)

### **INVERTER PART**

Symbol	Parameter	Condition	Ratings	Unit
V <sub>DD</sub>	Supply voltage	Applied between P-NU,NV,NW	400	V
V <sub>DD(surge)</sub>	Supply voltage (surge)	Applied between P-NU,NV,NW	450	V
V <sub>DSS</sub>	Drain-source voltage		500	V
±l₀	Each MOSFET drain current	T <sub>C</sub> = 25°C	5	Α
±l <sub>DP</sub>	Each MOSFET drain current (peak)	T <sub>C</sub> = 25°C, less than 1ms	10	Α
PD	Drain dissipation	T <sub>C</sub> = 25°C, per 1 chip	35.7	W
$T_{ch}$	Channel temperature	(Note 1)	-20~+150	°C

Note1: The maximum junction temperature rating of built-in power chips is 150°C(@Tc≤100°C). However, to ensure safe operation of DIPIPM, the average channel temperature should be limited to Tch(Ave)≤125°C (@Tc≤100°C).

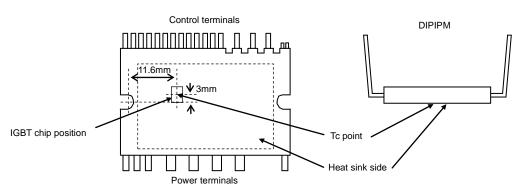
#### **CONTROL (PROTECTION) PART**

Symbol	Parameter	Condition	Ratings	Unit
VD	Control supply voltage	Applied between V <sub>P1</sub> -V <sub>NC</sub> , V <sub>N1</sub> -V <sub>NC</sub>	20	V
V <sub>DB</sub>	Control supply voltage	Applied between VUFB-U, VVFB-V, VWFB-W	20	V
V <sub>IN</sub>	Input voltage	Applied between $U_P$ , $V_P$ , $W_P$ - $V_{PC}$ , $U_N$ , $V_N$ , $W_N$ - $V_{NC}$	-0.5~V <sub>D</sub> +0.5	V
V <sub>FO</sub>	Fault output supply voltage	Applied between Fo-VNC	-0.5~V <sub>D</sub> +0.5	V
I <sub>FO</sub>	Fault output current	Sink current at Fo terminal	1	mA
V <sub>SC</sub>	Current sensing input voltage	Applied between CIN-V <sub>NC</sub>	-0.5~V <sub>D</sub> +0.5	V

#### TOTAL SYSTEM

Symbol	Parameter	Condition	Ratings	Unit
V <sub>DD(PROT)</sub>	Self protection supply voltage limit (Short circuit protection capability)			V
Tc	Module case operation temperature	Measurement point of Tc is provided in Fig.1	-20~+100	°C
T <sub>stg</sub>	Storage temperature		-40~+125	°C
V <sub>iso</sub>	Isolation voltage	60Hz, Sinusoidal, AC 1min, between connected all pins and heat sink plate	1500	Vrms

#### Fig. 1: T<sub>c</sub> MEASUREMENT POINT



#### THERMAL RESISTANCE

Symbol	Parameter	Condition	Limits			Unit
Symbol	Falanelei	Condition	Min.	Тур.	Max.	Unit
R <sub>th(ch-c)Q</sub>	Junction to case thermal resistance (Note2)	1/6 module	-	-	2.8	K/W
Note 2: Grea	Note 2: Grease with good thermal conductivity and long-term endurance should be applied evenly with about +100um~+200um on the contacting surface of					

DIPIPM and heat sink. The contacting thermal resistance between DIPIPM case and heat sink Rth(c-f) is determined by the thickness and the thermal conductivity of the applied grease. For reference, Rth(c-f) is about 0.3K/W (per 1/6 module, grease thickness: 20µm, thermal conductivity: 1.0W/m•k).

# **ELECTRICAL CHARACTERISTICS** ( $T_{ch} = 25^{\circ}C$ , unless otherwise noted) **INVERTER PART**

Symbol	Parameter	Condition		Limits			Unit	
Symbol	Falameter	Condition	Condition		Тур.	Max.	Unit	
V	Drain-source on-state	VD=VDB = 15V. VIN= 5V. ID= 5A	T <sub>ch</sub> = 25°C	-	0.60	0.80	Ω	
V <sub>DS(on)</sub>	resistance	$v_{D} = v_{DB} = 15v, v_{IN} = 5v, I_{D} = 5A$	T <sub>ch</sub> = 125°C	-	1.30	1.70	12	
V <sub>SD</sub>	Source-drain voltage drop	$V_{IN} = 0V, -I_D = 5A$		-	0.90	1.30	V	
t <sub>on</sub>				0.65	1.15	1.65	μs	
t <sub>C(on)</sub>		$V_{DD}$ = 300V, $V_{D}$ = $V_{DB}$ = 15V		-	0.35	0.55	μs	
t <sub>off</sub>	Switching times	I <sub>D</sub> = 5A, Tch= 125°C, V <sub>IN</sub> = 0↔5V		-	1.00	1.50	μs	
$t_{C(\text{off})}$		Inductive Load (upper-lower arm)	Inductive Load (upper-lower arm)		0.10	0.20	μs	
t <sub>rr</sub>				-	0.25	-	μs	
	Drain-source cut-off	<u> </u>	T <sub>ch</sub> = 25°C	-	-	1	mA	
IDSS	current	V <sub>DS</sub> =V <sub>DSS</sub>	T <sub>ch</sub> = 125°C	-	-	10	ША	

## **CONTROL (PROTECTION) PART**

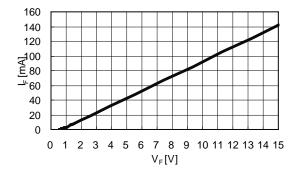
Symbol	Parameter	Condition		Limits			Unit
Symbol	Parameter			Min.	Тур.	Max.	Unit
1		Total of V <sub>P1</sub> -V <sub>NC</sub> , V <sub>N1</sub> -V <sub>NC</sub>	$V_D=15V, V_{IN}=0V$	-	-	2.80	
ID	Circuit current		V <sub>D</sub> =15V, V <sub>IN</sub> =5V	-	-	2.80	
1		Each part of V <sub>UFB</sub> -U,	$V_D = V_{DB} = 15V, V_{IN} = 0V$	-	-	0.10	mA
I <sub>DB</sub>		V <sub>VFB</sub> -V, V <sub>WFB</sub> -W	$V_D = V_{DB} = 15V, V_{IN} = 5V$	-	-	0.10	
V <sub>SC(ref)</sub>	Short circuit trip level	V <sub>D</sub> = 15V	(Note 3)	0.43	0.48	0.53	V
UV <sub>DBt</sub>	P-side Control supply		Trip level	7.0	10.0	12.0	V
$UV_{DBr}$	under-voltage protection(UV)	Tch ≤125°C	Reset level	7.0	10.0	12.0	V
$UV_{Dt}$	N-side Control supply		Trip level	10.3	-	12.5	V
UV <sub>Dr</sub>	under-voltage protection(UV)	Reset level		10.8	-	13.0	V
OTt	Over temperature protection	V <sub>D</sub> = 15V	Trip level	100	120	140	°C
OT <sub>rh</sub>	(OT) (Note4)	Detect LVIC temperature	Hysteresis of trip-reset	-	10	-	°C
$V_{\text{FOH}}$		$V_{SC}$ = 0V, $F_{O}$ terminal pulled u	ip to 5V by 10kΩ	4.9	-	-	V
$V_{\text{FOL}}$	Fault output voltage	$V_{SC} = 1V$ , $I_{FO} = 1mA$		-	-	0.95	V
t <sub>FO</sub>	Fault output pulse width		(Note 5)	20	-	-	μs
I <sub>IN</sub>	Input current	$V_{IN} = 5V$		0.70	1.00	1.50	mA
V <sub>th(on)</sub>	ON threshold voltage			-	2.10	2.60	
V <sub>th(off)</sub>	OFF threshold voltage	Applied between $U_P$ , $V_P$ , $W_P$ ,	UN, VN, WN-VNC	0.80	1.30	-	v
$V_{\text{th(hys)}}$	ON/OFF threshold hysteresis voltage	· · · · · · · · · · · · · · · · · · ·		0.35	0.65	-	
V <sub>F</sub>	Bootstrap Di forward voltage	$I_F$ =10mA including voltage drop	by limiting resistor (Note 6)	1.1	1.7	2.3	V
R	Built-in limiting resistance	Included in bootstrap Di		80	100	120	Ω

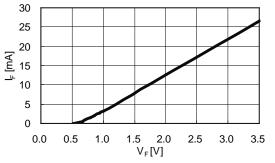
Note 3 : SC protection works for N-side only. Please select the external shunt resistance such that the SC trip-level is less than 1.7 times of the current rating. 4 : When the LVIC temperature exceeds OT trip temperature level(OT<sub>t</sub>), OT protection works and Fo outputs. In that case if the heat sink dropped off or fixed

loosely, don't reuse that DIPIPM. (There is a possibility that channel temperature of power chips exceeded maximum Tch(150°C).

5 : Fault signal Fo outputs when SC, UV or OT protection works. Fo pulse width is different for each protection modes. At SC failure, Fo pulse width is a fixed width (=minimum 20µs), but at UV or OT failure, Fo outputs continuously until recovering from UV or OT state. (But minimum Fo pulse width is 20µs.)
 6 : The characteristics of bootstrap Di is described in Fig.2.

Fig. 2 Characteristics of bootstrap Di V<sub>F</sub>-I<sub>F</sub> curve (@Ta=25°C) including voltage drop by limiting resistor (Right chart is enlarged chart.)

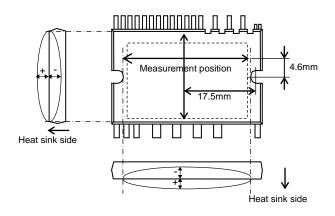




## **MECHANICAL CHARACTERISTICS AND RATINGS**

Parameter	Condition			Unit		
Falameter	Cond	Condition			Max.	Unit
Mounting torque	Mounting screw : M3 (Note 8)	Recommended 0.69N·m	0.59	0.69	0.78	N∙m
Terminal pulling strength	Control terminal: Load 4.9N Power terminal: Load 9.8N	EIAJ-ED-4701	10	-	-	s
Terminal bending strength	Control terminal: Load 2.45N Power terminal: Load 4.9N 90deg. bend	EIAJ-ED-4701	2	-	-	times
Weight			-	8.5	-	g
Heat-sink flatness	(Note 9) -50 -			100	μm	

Note 8: Plain washers (ISO 7089~7094) are recommended. Note 9: Measurement point of heat sink flatness



## **RECOMMENDED OPERATION CONDITIONS**

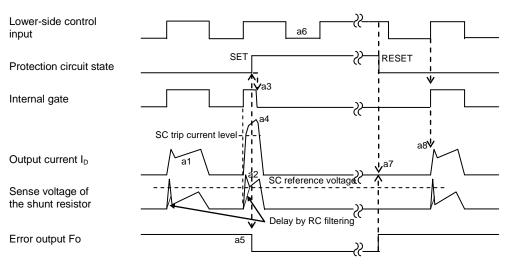
Symbol	Parameter	Condition			Limits		Unit	
Symbol	Falameter	Condition		Min.	Тур.	Max.	Unit	
V <sub>cc</sub>	Supply voltage	Applied between P-NU, NV, NW		0	300	400	V	
V <sub>D</sub>	Control supply voltage	Applied between $V_{P1}$ - $V_{NC}$ , $V_{N1}$ - $V_{NC}$		13.5	15.0	16.5	V	
V <sub>DB</sub>	Control supply voltage	Applied between VUFB-U, VVFB-V, VWFB-W		13.0	15.0	18.5	V	
$\Delta V_D, \Delta V_{DB}$	Control supply variation					+1	V/µs	
t <sub>dead</sub>	Arm shoot-through blocking time	For each input signal		1.0	-	-	μs	
f <sub>PWM</sub>	PWM input frequency	$T_{\rm C} \le 100^{\circ}$ C, Tch $\le 125^{\circ}$ C	$T_{\rm C} \le 100^{\circ}$ C, Tch $\le 125^{\circ}$ C		-	20	kHz	
	Allowable r.m.s. current	$V_{DD} = 300V, V_D = 15V, P.F = 0.8,$ Sinusoidal PWM	f <sub>PWM</sub> = 5kHz	-	-	2.5	Armo	
IO	Allowable I.M.S. current		f <sub>PWM</sub> = 15kHz	-	-	2.0	Arms	
PWIN(on)			(Note 11)		-	-		
PWIN(off)	Minimum input pulse width	(N		0.7	-	-	μs	
V <sub>NC</sub>	V <sub>NC</sub> variation	Between V <sub>NC</sub> -NU, NV, NW (including sur	ge)	-5.0	-	+5.0	V	
Tch	Channel temperature			-20	-	+125	°C	

Note 10: Allowable r.m.s. current depends on the actual application conditions. 11: DIPIPM might not make response if the input signal pulse width is less than PWIN(on), PWIN(off).

Fig. 3 Timing Charts of The DIPIPM Protective Functions

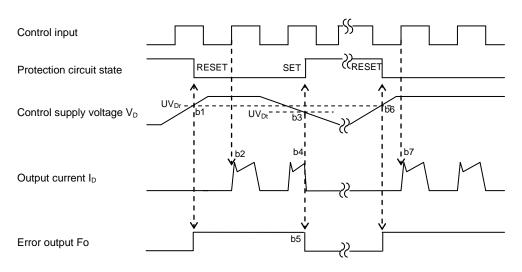
[A] Short-Circuit Protection (N-side only with the external shunt resistor and RC filter)

- a1. Normal operation: MOSFET ON and outputs current.
- a2. Short circuit current detection (SC trigger)
  - (It is recommended to set RC time constant 1.5~2.0µs so that MOSFET shut down within 2.0µs when SC.)
- a3. All N-side MOSFET's gates are hard interrupted.
- a4. All N-side MOSFETs turn OFF.
- a5.  $F_{\text{O}}$  outputs for  $t_{\text{Fo}}\text{=}\text{minimum}$  20µs.
- a6. Input = "L": MOSFET OFF
- a7. Fo finishes output, but MOSFETs don't turn on until inputting next ON signal (L $\rightarrow$ H).
- (MOSFET of each phase can return to normal state by inputting ON signal to each phase.) a8. Normal operation: MOSFET ON and outputs current.



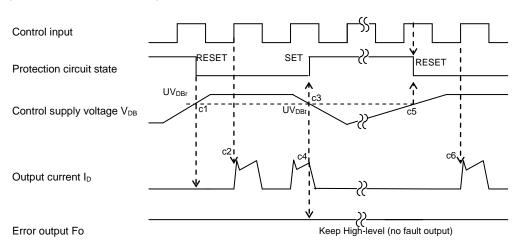
[B] Under-Voltage Protection (N-side, UV<sub>D</sub>)

- b1. Control supply voltage V<sub>D</sub> exceeds under voltage reset level (UV<sub>Dr</sub>), but MOSFET turns ON by next ON signal (L $\rightarrow$ H). (MOSFET of each phase can return to normal state by inputting ON signal to each phase.)
- b2. Normal operation: MOSFET ON and outputs current.
- b3.  $V_D$  level drops to under voltage trip level. (UV<sub>Dt</sub>).
- b4. All N-side MOSFETs turn OFF in spite of control input condition.
- b5. Fo outputs for  $t_{Fo}$ =minimum 20µs, but output is extended during V<sub>D</sub> keeps below UV<sub>Dr</sub>.
- b6.  $V_{\text{D}}$  level reaches  $UV_{\text{Dr}}.$
- b7. Normal operation: MOSFET ON and outputs current.



[C] Under-Voltage Protection (P-side, UV<sub>DB</sub>)

- c1. Control supply voltage  $V_{DB}$  rises. After the voltage reaches under voltage reset level UV<sub>DBr</sub>, MOSFET turns on by next ON signal (L $\rightarrow$ H).
- c2. Normal operation: MOSFET ON and outputs current.
- c3.  $V_{DB}$  level drops to under voltage trip level (UV<sub>DBt</sub>).
- c4. MOSFET of the correspond phase only turns OFF in spite of control input signal level, but there is no Fo signal output.
- c5.  $V_{DB}$  level reaches  $UV_{DBr}$ .
- c6. Normal operation: MOSFET ON and outputs current.



[D] Over Temperature Protection (N-side, Detecting LVIC temperature)

- d1. Normal operation: MOSFET ON and outputs current.
- d2. LVIC temperature exceeds over temperature trip level(OT<sub>t</sub>).
- d3. All N-side MOSFETs turn OFF in spite of control input condition.
- d4. Fo outputs for t<sub>F0</sub>=minimum 20µs, but output is extended during LVIC temperature keeps over OT<sub>t</sub>.
- d5. LVIC temperature drops to over temperature reset level.
- d6. Normal operation: MOSFET turns on by next ON signal (L $\rightarrow$ H).
  - (MOSFET of each phase can return to normal state by inputting ON signal to each phase.)

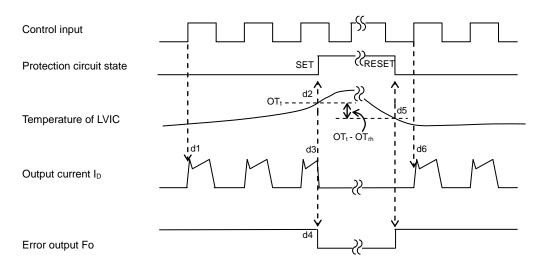
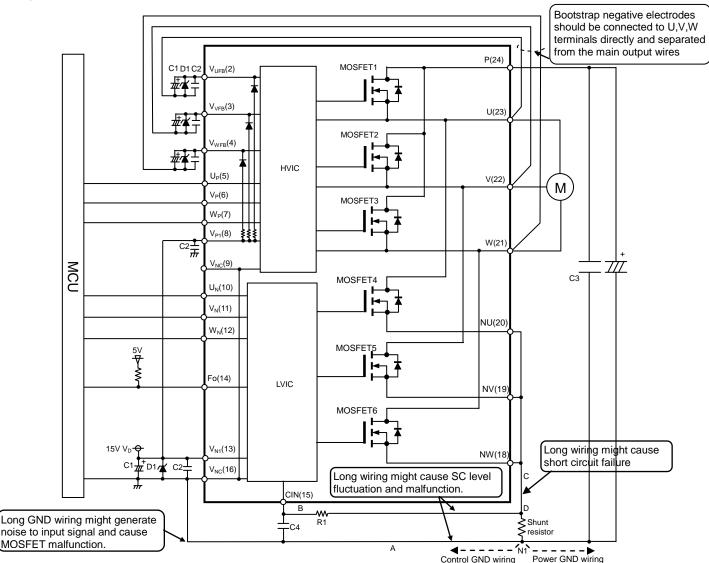
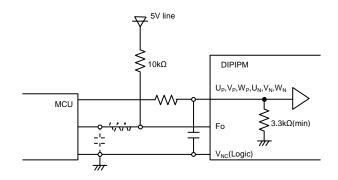


Fig. 4 Example of Application Circuit



- (1) If control GND is connected with power GND by common broad pattern, it may cause malfunction by power GND fluctuation. It is recommended to connect control GND and power GND at only a point N1 (near the terminal of shunt resistor).
- (2) It is recommended to insert a Zener diode D1(24V/1W) between each pair of control supply terminals to prevent surge destruction.
  (3) To prevent surge destruction, the wiring between the smoothing capacitor and the P, N1 terminals should be as short as possible.
- Generally a 0.1-0.22µF snubber capacitor C3 between the P-N1 terminals is recommended.
  (4) R1, C4 of RC filter for preventing protection circuit malfunction is recommended to select tight tolerance, temp-compensated type.
- The time constant R1C4 should be set so that SC current is shut down within 2µs. (1.5µs~2µs is general value.) SC interrupting time might vary with the wiring pattern, so the enough evaluation on the real system is necessary.
- (5) To prevent malfunction, the wiring of A, B, C should be as short as possible.
- (6) The point D at which the wiring to CIN filter is divided should be near the terminal of shunt resistor. NU, NV, NW terminals should be connected at near NU, NV, NW terminals.
- (7) All capacitors should be mounted as close to the terminals as possible. (C1: good temperature, frequency characteristic electrolytic type and C2:0.22µ-2µF, good temperature, frequency and DC bias characteristic ceramic type are recommended.)
- (8) Input drive is High-active type. There is a minimum 3.3kΩ pull-down resistor in the input circuit of IC. To prevent malfunction, the wiring of each input should be as short as possible. When using RC coupling circuit, make sure the input signal level meet the turn-on and turn-off threshold voltage.
- (9) Fo output is open drain type. It should be pulled up to MCU or control power supply (e.g. 5V,15V) by a resistor that makes I<sub>Fo</sub> up to 1mA. (I<sub>FO</sub> is estimated roughly by the formula of control power supply voltage divided by pull-up resistance. In the case of pulled up to 5V, 10kΩ (5kΩ or more) is recommended.)
- (10) Thanks to built-in HVIC, direct coupling to MCU without any opto-coupler or transformer isolation is possible.
- (11) Two V<sub>NC</sub> terminals (9 & 16 pin) are connected inside DIPIPM, please connect either one to the 15V power supply GND outside and leave another one open.
- (12) If high frequency noise superimposed to the control supply line, IC malfunction might happen and cause DIPIPM erroneous operation. To avoid such problem, line ripple voltage should meet dV/dt ≤+/-1V/µs, Vripple≤2Vp-p.
- (13) For DIPIPM, it isn't recommended to drive same load by parallel connection with other phase MOSFET or other DIPIPM.

Fig. 5 MCU I/O Interface Circuit

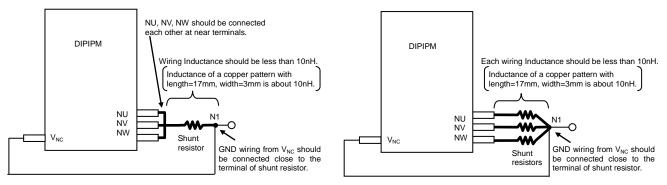


Note)

Design for input RC filter depends on PWM control scheme used in the application and wiring impedance of the printed circuit board. DIPIPM input signal interface integrates a minimum  $3.3k\Omega$ pull-down resistor. Therefore, when inserting RC filter, it is necessary to satisfy turn-on threshold voltage requirement.

Fo output is open drain type. It should be pulled up to control power supply (e.g. 5V, 15V) with a resistor that makes Fo sink current  $I_{Fo}~$  1mA or less. In the case of pulled up to 5V supply, 10k $\Omega~$ (5k $\Omega$  or more) is recommended.

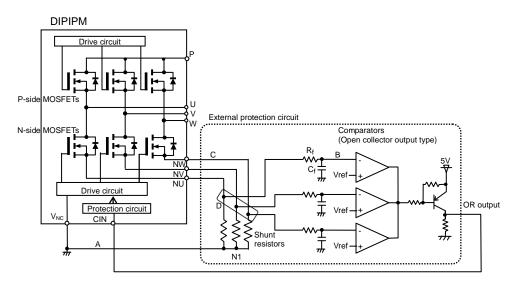
#### Fig. 6 Pattern Wiring Around the Shunt Resistor



Low inductance shunt resistor like surface mounted (SMD) type is recommended.

#### Fig. 7 Pattern Wiring Around the Shunt Resistor (for the case of open source)

When DIPIPM is operated with three shunt resistors, voltage of each shunt resistor cannot be input to CIN terminal directly. In that case, it is necessary to use the external protection circuit as below.



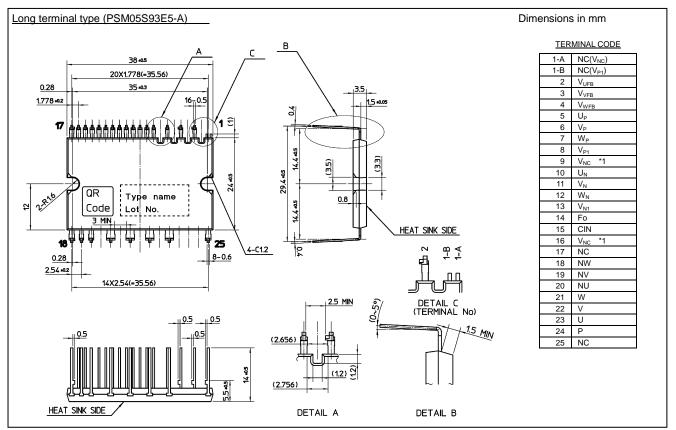
(1) It is necessary to set the time constant R<sub>i</sub>C<sub>f</sub> of external comparator input so that MOSFET stops within 2µs when short circuit occurs. SC interrupting time might vary with the wiring pattern, comparator speed and so on.

(2) It is recommended for the threshold voltage Vref to set to the same rating of short circuit trip level (Vsc(ref): typ. 0.48V).

(3) Select the external shunt resistance so that SC trip-level is less than specified value (=1.7 times of rating current).

- (4) To avoid malfunction, the wiring A, B, C should be as short as possible.
- (5) The point D at which the wiring to comparator is divided should be close to the terminal of shunt resistor.
- (6) OR output high level when protection works should be over 0.53V (=maximum Vsc(ref) rating).

## Fig. 8 Package Outlines



1) 9 & 16 pins ( $V_{NC}$ ) are connected inside DIPIPM, please connect either one to the control power supply GND outside and leave another one open.

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**Revision Record** 

Rev.	Date	Page	Revised contents
1	10/15/2013	-	New

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